

Adding “Process Algebra” to TLA

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This is a rough first draft of some very sweet syntactic sugar for defining TLA actions and associated predicates, inspired by process algebra. The first part describes the notation; the second part contains some handwaving about how one might use process-algebra style reasoning to verify specifications written in this style. I think the first part is fairly reasonable; the verification part is still pretty kludgy and needs a lot of work.

1 Specification

I first describe the notation in terms of a simple example. I then indicate the general notation and approximately what it means.

1.1 An Example

The example is a specification of a simple, single-user memory. The user sends either a $\langle \text{“Read”}, l \rangle$ request to read location l or a $\langle \text{“Write”}, l, v \rangle$ request to set location l to v . The memory responds to a read request with $\langle \text{“OK”}, v \rangle$, where v is the current value of location l , and it responds to a write request with $\langle \text{“OK”} \rangle$. No requests need ever occur, but the memory must eventually respond to every request.

The specification is a bit more complicated than necessary because it changes the memory with a separate, internal action. I did that to make the example a bit more interesting. I assume that the action $Send(v, c)$, which sends the value v over channel c , is already defined. I let $Locs$ and $Vals$ be the sets of possible memory locations and memory values, and $InitMem$ be the set of possible initial memory values. I use the TLA notation in which $[x \text{ EXCEPT } ![i] = u]$ is array (function) \hat{x} that is the same as x except $\hat{x}[i] = u$.

Here is the specification:

$$\mathbf{ProcAction} \ N(pc) \triangleq$$

$$\left(\bigoplus_{l \in Locs} \left(Send(\langle \text{“Rd”}, l \rangle, c)_{mem}; \ rr : Send(\langle \text{“OK”}, mem[l] \rangle)_{mem} \right) \right. \\ \left. \bigoplus_{v \in Vals} Send(\langle \text{“Wr”}, l, v \rangle, c)_{mem}; \ rw : \left((mem' = [mem \text{ EXCEPT } ![l] = v])_c; \ Send(\langle \text{“OK”} \rangle)_{mem} \right) \right)^*$$

$$Spec \triangleq \exists mem, pc : \\ \wedge (mem' \in InitMem) \wedge At(N(pc)) \\ \wedge \Box [N(pc)]_{\langle mem, pc \rangle} \\ \wedge \forall l \in Locs : \wedge WF_{pc}(rr(pc, l)) \\ \wedge \forall v \in Vals : WF_{pc}(rw(pc, l, v))$$

The **ProcAction** command defines the action $N(pc)$ to equal the following, where x , y , and z are arbitrary constants, and the constants x , y , z , rr , and rw are assumed to be distinct.

$$\exists l \in Locs : \\ \vee \vee \wedge pc = x \\ \wedge pc' = \langle rr, l \rangle \\ \wedge Send(\langle \text{“Rd”}, l \rangle, c) \wedge (mem' = mem) \\ \vee \wedge pc = \langle rr, l \rangle \\ \wedge pc' = x \\ \wedge Send(\langle \text{“OK”}, mem[l] \rangle) \wedge (mem' = mem) \\ \vee \exists v \in Vals : \\ \vee \wedge pc = x \\ \wedge pc' = \langle rw, l, v \rangle \\ \wedge Send(\langle \text{“Wr”}, l, v \rangle, c) \wedge (mem' = mem) \\ \vee \wedge pc = \langle rw, l, v \rangle \\ \wedge pc' = \langle z, l, v \rangle \\ \wedge (mem' = [mem \text{ EXCEPT } ![l] = v]) \wedge (c' = c) \\ \vee \wedge pc = \langle z, l, v \rangle \\ \wedge pc' = x \\ \wedge Send(\langle \text{“OK”} \rangle, c) \wedge (mem' = mem)$$

It also makes the following definitions (among others):

$$\begin{aligned}
At(N(pc)) &\triangleq pc = x \\
rr(pc, l) &\triangleq \wedge pc = \langle rr, l \rangle \\
&\quad \wedge pc' = x \\
&\quad \wedge Send(\langle \text{“OK”}, mem[l] \rangle) \wedge (mem' = mem) \\
rw(pc, l, v) &\triangleq \vee \wedge pc = \langle rw, l, v \rangle \\
&\quad \wedge pc' = \langle z, l, v \rangle \\
&\quad \wedge (mem' = [mem \text{ EXCEPT } ![l] = v]) \wedge (c' = c) \\
&\quad \vee \wedge pc = \langle rw, l, v \rangle \\
&\quad \wedge pc' = x \\
&\quad \wedge Send(\langle \text{“OK”} \rangle, c) \wedge (mem' = mem)
\end{aligned}$$

1.2 The General Notation

The right-hand side of a **ProcAction** statement is an expression formed by combining ordinary TLA actions with the following additional operators¹

$$; \quad \oplus \quad \bigoplus \quad (\dots)^* \quad \uparrow \quad \parallel \quad \|\|$$

If A is an ordinary TLA action, then we let A_f be an abbreviation for $A \wedge (f' = f)$, allowing us to write UNCHANGED expressions more compactly. The additional operators have the following intuitive interpretation.

$A; B$ — Do A then B .

$A \oplus B$ — Do A or B .

$\bigoplus_{v \in S} A(v)$ — Do $A(v)$ for some $v \in S$.

$\bigoplus_v A(v)$ — Do $A(v)$ for some v .

$(A)^*$ — Keep doing A actions forever, or until the loop is exited (see below).

$A \uparrow$ — Do A , then exit from the innermost containing $(\dots)^*$.

$A \parallel B$ — Interleave A and B . (If A and B are ordinary TLA actions, then $A \parallel B$ is equivalent, in a sense explained below, to $A; B \oplus B; A$.)

¹I'm not completely convinced that \parallel and $\|\|$ are necessary.

$\prod_{v \in S} A(v)$ and $\prod_v A(v)$ — Interleave the $A(v)$ for all $v \in S$ and all v , respectively.

A label can be attached to any subexpression. (All labels must be unique within the **ProcAction** statement.) If the subexpression $l : A$ appears in a **ProcAction** statement, then the following actions and predicates are defined, where pc is the **ProcAction** variable and v_1, \dots, v_n is the sequence of bound \oplus variables containing the subexpression.

$l(pc, v_1, \dots, v_n)$ A TLA action. A step of this action consists of performing a step of one of the subactions of A .

$At(l(pc, v_1, \dots, v_n))$ The predicate asserting that control is at the beginning of the subexpression.

$In(l(pc, v_1, \dots, v_n))$ The predicate asserting that control is at the beginning or somewhere inside the subexpression.

$After(l(pc, v_1, \dots, v_n))$ The predicate asserting that control is immediately after the subexpression.

It's fairly straightforward to give a formal semantics to the **ProcAction** statement with the operators I've defined so far. For future reference, I'll sketch how it's done.

Let a primitive action be an expression of the form $l : A$, where A is an ordinary TLA action. A p-action is an expression constructed from such primitive actions using the operators “;”, \oplus , etc., where the labels l are all distinct. A **ProcAction** statement defines a p-action for the entire right-hand side, as well as for each label. Assume a control variable pc , distinct from all variables that appear in primitive actions. We will define a semantics of p-actions by defining, for each p-action P :

- A collection of constants L_P called *labels*, with a distinguished element at_P called the *at* label.
- A collection of actions A_P of the form $(pc = l) \wedge (pc' = k) \wedge A$, where A is an ordinary TLA action in which pc does not occur, $l \in L_P$, and k is either a label in L_P or one of the special constants “Done” or “Exit”.

We can then define

$$\begin{aligned} Act(P) &\triangleq \exists A \in A_P : A \\ At(P) &\triangleq pc = at_P \\ In(P) &\triangleq pc \in L_P \\ After(P) &\triangleq pc = \text{“Done”} \end{aligned}$$

These are the actions and predicates described informally above, where if P has the label l and v_1, \dots, v_n are the enclosing \bigoplus variables, then we write $l(pc, v_1, \dots, v_n)$ instead of $Act(P)$, $At(l(pc, v_1, \dots, v_n))$ instead of $At(P)$, etc.

We then recursively define L_P , at_P , and A_P for any p-action P . Here are some of the recursive definitions:

- If P is the primitive action $l : A$, then $L_P \triangleq \{l\}$ and A_P contains the single action $(pc = l) \wedge (pc' = \text{“Done”}) \wedge A$.
- If $P = \widehat{P1}; P2$, then $L_P \triangleq L_{P1} \cup L_{P2}$; $at_P \triangleq at_{P1}$; and $A_P \triangleq \widehat{A_{P1}} \cup A_{P2}$, where $\widehat{A_{P1}}$ consists of the actions of A_{P1} with at_{P2} substituted for “Done”.
- If $P = \bigoplus_{v \in S} Q$, then L_P is the set consisting of at_Q together with all elements of the form $\langle v, l \rangle$ with $v \in S$ and $l \in L_Q$, $l \neq at_Q$; and A_P consists of the set of all actions obtained from actions in A_Q by replacing every label l in L_Q different from at_Q by $\langle v, l \rangle$, for all $v \in S$.
- If $P = P1 \parallel P2$, then L_P is the set of all labels $\langle l1, l2 \rangle$, where li is either in L_{P1} or equals “Done”, excluding $\langle \text{“Done”}, \text{“Done”} \rangle$; $at_P \triangleq \langle at_{P1}, at_{P2} \rangle$; and $A_P \triangleq \widehat{A_{P1}} \cup \widehat{A_{P2}}$, where $\widehat{A_{P1}}$ consists of all actions of the form $(pc = \langle l, l2 \rangle) \wedge (pc' = \langle k, l2 \rangle) \wedge A$, for some $(pc = l) \wedge (pc' = k) \wedge A$ in A_{P1} and some $l2$ in L_{P2} or equal to “Done”, except writing $pc' = \text{“Done”}$ instead of $pc' = \langle \text{“Done”}, \text{“Done”} \rangle$, and $pc' = \text{“Exit”}$ instead of $pc' = \langle \text{“Exit”}, l2 \rangle$.

The definitions for the other constructs are similar.

1.3 Is This Enough?

I don’t see any need for additional operators. I think that the only missing standard CCS operators are hiding and more general recursion than simple looping. Hiding is expressed with the ordinary TLA quantifier \exists . It shouldn’t be hard to extend the language of p-actions to allow recursive definitions. For a recursively defined p-action P , the sets L_P and A_P become infinite, but that shouldn’t cause any problem. However, I don’t think this kind of recursive definition is necessary. I think that recursion should be restricted to the definitions of data types. For example, here’s a specification of a bounded buffer, with input channel in and output channel out , in

which a *Put* request waits if the buffer is full, and a *Get* request waits if the buffer is empty.

$$\begin{aligned}
\mathbf{ProcAction} \ B(pc) &\triangleq \\
& \left(\bigoplus_{v \in Vals} \text{Send}(v, in)_{\langle q, out \rangle}; \right. \\
& \quad \left. p : (\text{Len}(q) \neq \text{Max}) \wedge (q' = q \circ \langle v \rangle) \wedge \text{Send}(\text{"OK"}, in)_{out} \right)^* \\
& \parallel \\
& \left(\text{Send}(\text{"Get"}, out)_{\langle q, in \rangle}; \right. \\
& \quad \left. g : (q \neq \langle \rangle) \wedge (q' = \text{Tail}(q)) \wedge \text{Send}(\text{Head}(q), out)_{in} \right)^*
\end{aligned}$$

$$\begin{aligned}
\text{Spec} &\triangleq \exists q, pc : \wedge (q = \langle \rangle) \wedge \text{At}(B(pc)) \\
& \quad \wedge \square [B(pc)]_{\langle q, in, out, pc \rangle} \\
& \quad \wedge \text{WF}_{pc}(g(pc)) \wedge \forall v \in Vals : \text{WF}_{pc}(p(pc, v))
\end{aligned}$$

Here's an alternative way of writing the specification that does not use the \parallel construct.

$$\begin{aligned}
\mathbf{ProcAction} \ \text{Put}(pc) &\triangleq \\
& \left(\bigoplus_{v \in Vals} \text{Send}(v, in)_{\langle q, out \rangle}; \right. \\
& \quad \left. p : (\text{Len}(q) \neq \text{Max}) \wedge (q' = q \circ \langle v \rangle) \wedge \text{Send}(\text{"OK"}, in)_{out} \right)^* \\
\mathbf{ProcAction} \ \text{Get}(pc) &\triangleq \\
& \left(\text{Send}(\text{"Get"}, out)_{\langle q, in \rangle}; \right. \\
& \quad \left. g : (q \neq \langle \rangle) \wedge (q' = \text{Tail}(q)) \wedge \text{Send}(\text{Head}(q), out)_{in} \right)^* \\
\text{Spec} &\triangleq \\
& \exists q, pc1, pc2 : \\
& \quad \wedge (q = \langle \rangle) \wedge \text{At}(\text{Put}(pc1)) \wedge \text{At}(\text{Get}(pc2)) \\
& \quad \wedge \square [\text{Put}(pc1)]_{in} \wedge \square [\text{Get}(pc2)]_{out} \wedge \square [(pc1' \neq pc1) \vee (pc2' \neq pc2)]_q \\
& \quad \wedge \text{WF}_{pc}(g(pc2)) \wedge \forall v \in Vals : \text{WF}_{pc}(p(pc1, v))
\end{aligned}$$

One might think of adding a synchronous parallel composition operator $\parallel\parallel$, where $A\parallel\parallel B$ is equivalent to $A; B \oplus B; A \oplus A \wedge B$ for primitive actions A and B . However, I think that conjunction of temporal formulas can be used just as easily to express synchronous composition.

2 Verification

Those of you old enough to remember

AUTHOR = "Susan Owicki and Leslie Lamport",

TITLE = "Proving Liveness Properties of Concurrent
 Programs",
 JOURNAL = toplas,
 volume = 4,
 number = 3,
 YEAR = 1982,
 month = JUL,
 PAGES = "455--495"

will recognize the *At*, *In*, and *After* control predicates. What I've done is define a tiny programming language. I know from experience that these control predicates are all you need to prove properties about programs. However, I expect that we can simulate the process-algebra style of proof rules for reasoning about p-actions

Here's a quick sketch of my idea for how this is done. I'll stick to proving safety properties. We have to prove

$$\exists z : \text{Init1} \wedge \square[N1]_{\langle x, z \rangle} \Rightarrow \exists y : \text{Init2} \wedge \square[N2]_{\langle x, y \rangle}$$

For this, it suffices to find a refinement mapping—a function \bar{y} of x and z —and prove $\text{Init1} \Rightarrow \overline{\text{Init2}}$ and

$$[N1 \wedge I]_{\langle x, z \rangle} \Rightarrow [\overline{N2}]_{\langle x, \bar{y} \rangle} \quad (1)$$

where I is a suitable invariant and overbarbing means substituting \bar{y} for y . I'll ignore initial conditions and just consider (1). I'll suppose $N1$ and $N2$ are written as p-actions with control variables $pc1$ and $pc2$, respectively.² Then (1) can be written

$$[\text{Act}(N1) \wedge I]_{\langle x, z, pc1 \rangle} \Rightarrow [\overline{\text{Act}(N2)}]_{\langle x, \bar{y}, \overline{pc2} \rangle} \quad (2)$$

In general, \bar{y} will be a function of x and z , and we'll we'll wind up defining $\overline{pc2}$ to be a function of $pc1$, so (2) reduces to

$$\text{Act}(N1) \wedge I \Rightarrow [\overline{\text{Act}(N2)}]_{\langle x, \bar{y}, \overline{pc2} \rangle} \quad (3)$$

More precisely, we assume that we're given the refinement mapping \bar{y} for the explicit internal variables y (excluding $pc2$), and we have to show that there exists a function $\overline{pc2}$ of $pc1$ so that (3) holds. The idea is to do this recursively for the subexpressions of $N1$ and $N2$.

²In general, $N1$ and $N2$ may just include p-actions as disjuncts. In this case, the type of verification I describe here is just part of the reasoning.

Let A and B be p-actions with control variables $pc1$ and $pc2$, respectively. Let $C \xrightarrow[f|g]{A|B} D$ mean that there exists a mapping λ from L_A to $L_B \cup \{\text{“Done”}, \text{“Exit”}\}$ with $\lambda(at_A) = at_B$ such that $(f' = f) \Rightarrow (g' = g)$ and

$$\begin{aligned} & \wedge \forall l \in L_A : \wedge (pc1 = l) \Rightarrow (pc2 = \lambda(l)) \\ & \quad \wedge (pc1' = l) \Rightarrow (pc2' = \lambda(l)) \\ & \wedge (pc1' = \text{“Done”}) \Rightarrow (pc2' = \text{“Done”}) \\ & \wedge (pc1' = \text{“Exit”}) \Rightarrow (pc2' = \text{“Exit”}) \\ & \wedge C \\ & \Rightarrow D \vee ((g' = g) \wedge (pc2' = pc2)) \end{aligned}$$

Let's now let \overline{F} be the formula obtained by substituting \overline{y} for y in F , and let $\overline{\overline{F}}$ be the formula obtained by substituting $\overline{pc2}$ for $pc2$ in \overline{F} . Let's also abbreviate $Act(A)$ to A . Then (3) becomes

$$N1 \wedge I \Rightarrow [\overline{\overline{N2}}]_{\langle x, \overline{y}, \overline{pc2} \rangle} \quad (4)$$

To prove that there exists $\overline{pc2}$ for which (4) holds, it suffices to prove

$$N1 \wedge I \xrightarrow[\langle x, y \rangle | \langle x, \overline{y} \rangle]{N1|N2} \overline{\overline{N2}}$$

We do this by applying “algebraic” rules to decompose the problem. First, there is a rule for primitive actions and for each operator—for example:

- If A and B are primitive actions, $(f' = f) \Rightarrow (g' = g)$, and $I \wedge A \Rightarrow [B]_g$, then $I \wedge A \xrightarrow[f|g]{A|B} B$.
- If $A1 \xrightarrow[f|g]{A1|B1} B1$ and $A2 \xrightarrow[f|g]{A2|B2} B2$, then $A1; A2 \xrightarrow[f|g]{A1; A2 | B1; B2} B1; B2$.
- If $A \xrightarrow[f|g]{A|B} B$ for all v , then $\bigoplus_v A \xrightarrow[f|g]{\bigoplus_v A | \bigoplus_v B} \bigoplus_v B$.

The relation $\xrightarrow[f|g]{A|B}$ also obeys some general logical rules, such as:

- $I \Rightarrow (C \xrightarrow[f|g]{A|B} D)$ iff $(I \wedge C) \xrightarrow[f|g]{A|B} D$.
- Transitivity: $X \xrightarrow[f|g]{A|B} Y$ and $Y \xrightarrow[g|h]{B|C} Z$ imply $X \xrightarrow[f|h]{A|C} Z$.

We can also define an equivalence relation $\stackrel{f}{\Leftrightarrow}$, where $A \stackrel{f}{\Leftrightarrow} B$ iff $A \stackrel{A|B}{f|f} \rightarrow B$ and $B \stackrel{B|A}{f|f} \rightarrow A$. For example, if A and B are primitive actions, then

$$A \| B \stackrel{f}{\Leftrightarrow} A; B \oplus B; A$$

for any f . Another useful equivalence is $(A; f' = f) \stackrel{f}{\Leftrightarrow} A$, which expresses stuttering equivalence. The relation $\stackrel{f}{\Leftrightarrow}$ should play the role of bisimulation equivalence in process algebra.